Contact Mechanics and Elements of Tribology

Lecture 7.

Lubrication and Sealing

Andrei G. Shvarts & Vladislav A. Yastrebov

MINES ParisTech, PSL Research University, Centre des Matériaux, CNRS UMR 7633, Evry, France

@ Centre des Matériaux
February 14, 2019

Outline

Acknowledgment:
Course "Scientific Computing with Applications in Tribology"
A. Almqvist, F. Pérez-Ràfols
Luleå University of Technology, Sweden, 7-9 February 2017

Lubrication: what is it?

- **Lubrication:** technique to reduce friction and wear between relatively moving surfaces by adding a solid/liquid/gas lubricant
- Studied in **Tribology** (Greek: *tribo* - "to rub", *logy* - "study of")
  'The Jost Report' (1966):
  cost of friction, wear and corrosion to UK economy P. Jost (1966)
- Applications:
  - gears
  - bearings
  - piston heads
  - human joints
  - seals
  - cams
  - metal forming
  - HDD ...
- Recent report (2017):
  23% of total world energy losses come from tribological contacts (20% friction, 3% wear)

  K. Holmberg, A. Erdemir, *Friction* (2017)

Lubricant over gears
www.iselinc.com

Lubricating a bike chain
www.madegood.org

Lubrication: what is it?

- **Lubrication:** technique to reduce friction and wear between relatively moving surfaces by adding a solid/liquid/gas lubricant
- Studied in **Tribology** (Greek: *tribo* - "to rub", *logy* - "study of")
  'The Jost Report' (1966):
  cost of friction, wear and corrosion to UK economy P. Jost (1966)
- Applications:

- gears	- seals
- bearings	- cams
- piston heads	- metal forming
- human joints	- HDD ...

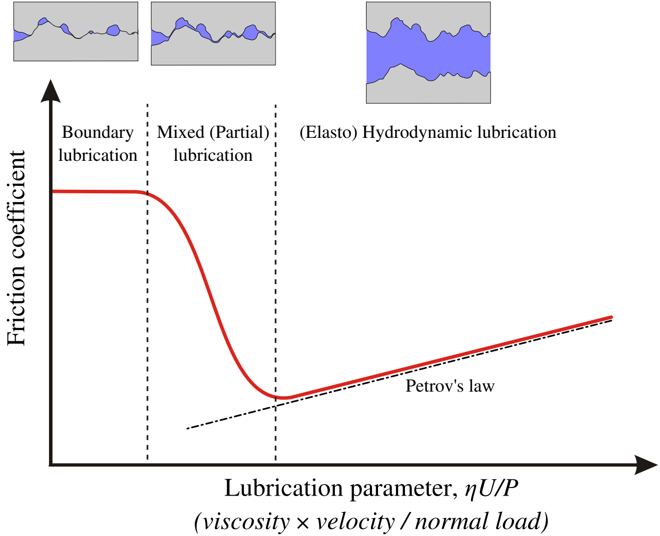
- Recent report (2017):
  23% of total world energy losses come from tribological contacts (20% friction, 3% wear)

  K. Holmberg, A. Erdemir, *Friction* (2017)

Lubricant over gears
www.efficientplantmag.com

Lubricated roller bearing
www.bearingtips.com

Lubrication regimes: Stribeck curve

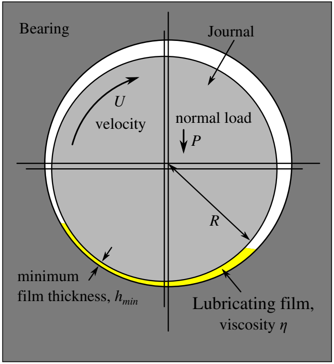


Adapted from `www.wikipedia.org`

R. Stribeck (1901)

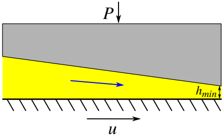
Hydrodynamic lubrication (HL)

- Conforming surfaces
- No elastic effect
- Normal load fully supported by thin fluid film
- $h_{\min} = f(P, U, \eta, R)$
- $p \leq 5$ MPa, $h_{\min} > 1\ \mu$m

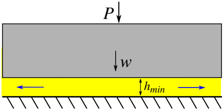


Concentric journal
Adapted from www.wikipedia.org

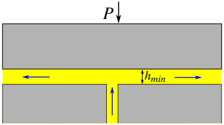
- Mechanism of pressure development in fluid film:



Slider bearing



Squeeze film bearing



Externally pressurized bearing

Newtonian fluid

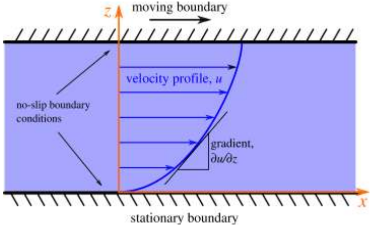
- Viscous stresses in flowing fluid are linearly proportional to the strain rate - the gradient of the velocity:

$$\tau = \eta \frac{\partial u}{\partial z}$$

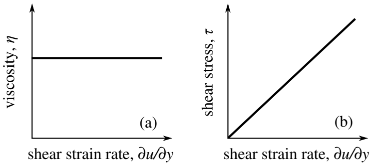
  - τ is the shear stress in the fluid
  - η is the viscosity (absolute, or dynamic) of the fluid
  - $\frac{\partial u}{\partial y}$ is the shear strain rate

- In general 3D case for arbitrary coordinate system:

$$\tau_{ij} = \eta \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$



Laminar shear of fluid between two rigid plates



Properties of Newtonian fluid:
(a) viscosity vs shear strain rate
(b) shear stress vs shear strain rate

- Shear stress:

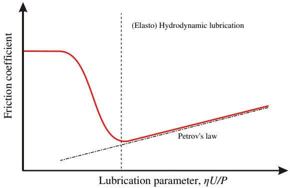
$$\tau = \eta \frac{\partial u}{\partial z} = \eta \frac{U}{h}$$

- Frictional reaction:

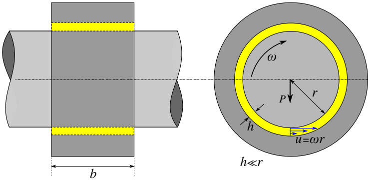
$$T = A\tau = (2\pi r b)\,\eta \frac{U}{h}$$

- The coefficient of friction:

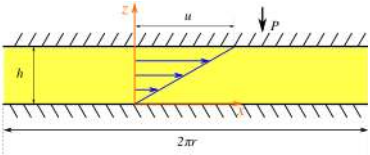
$$\mu = \frac{T}{P} = \frac{2\pi r b}{h} \frac{\eta U}{P}$$



Petrov's law
N.P. Petrov (1883)



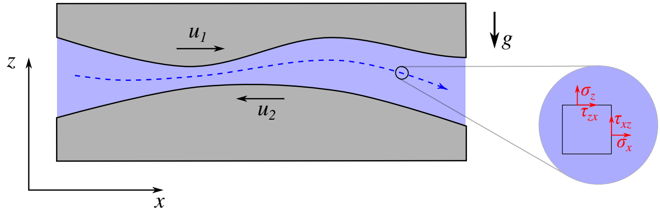
Concentric journal bearing



Developed journal and bearing surfaces

r	radius of journal
b	width of journal
U	linear velocity
P	normal load
h	radial clearance

Stresses on the surface of a fluid element



- Stresses on the surface of a fluid element:

$$\tau_{ij} = \eta\left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i}\right), \quad \tau_{ij} = \tau_{ji}$$

$$\sigma_i = -p - \frac{2}{3}\eta\nabla\cdot\underline{\boldsymbol{u}} + 2\eta\frac{\partial u_i}{\partial x_i}$$

η	absolute viscosity
p	hydrostatic pressure
x_i	coordinates
u_i	velocity componets
g	acceleration of gravity

Navier-Stokes equations

- Newton's second law of motion for a fluid element:

$$\underbrace{\rho\frac{D\underline{u}}{Dt}}_{\text{inertia forces}} = \underbrace{\rho\underline{g}}_{\text{body forces}} + \underbrace{\nabla\cdot\underline{\underline{\sigma}}}_{\text{surface forces}}$$

- Material derivative:

$$\underbrace{\frac{Du}{Dt}}_{\text{total derivative}} = \underbrace{\frac{\partial u}{\partial t}}_{\text{local derivative}} + \underbrace{u\frac{\partial u}{\partial x} + v\frac{\partial u}{\partial y} + w\frac{\partial u}{\partial z}}_{\text{convective derivative}}$$

- Navier-Stokes equations:

$$\rho\frac{D\underline{u}}{Dt} = \rho\underline{g} - \nabla p - \frac{2}{3}\nabla\left(\eta\nabla\cdot\underline{u}\right) + 2\left(\nabla\cdot(\eta\nabla)\right)\underline{u} + \nabla\times\left(\eta(\nabla\times\underline{u})\right)$$

- 4 unknowns: u, v, w, p; 3 equations + the continuity equation

Continuity equation

- Flux is a mass of fluid flowing per unit time through a unit area:

$$\underline{\boldsymbol{q}} = \rho \underline{\boldsymbol{u}}$$

- Conservation of mass: outflow of mass from a volume equals to decrease of mass within the volume (integral form):

$$\frac{dm}{dt} + \oiint_S (\underline{\boldsymbol{q}} \cdot \underline{\boldsymbol{n}})\, dS = 0$$

- The divergence theorem:

$$\oiint_S (\underline{\boldsymbol{q}} \cdot \underline{\boldsymbol{n}})\, dS = \iiint_V (\nabla \cdot \underline{\boldsymbol{q}})\, dV$$

- Differential form of continuity equation:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \underline{\boldsymbol{u}}) = 0$$

- If density ρ is constant: $\nabla \cdot \underline{\boldsymbol{u}} = 0$

Towards the Reynolds equation

- Introducing dimensionless variables:

$$X = \frac{x}{l_0}, \quad Y = \frac{y}{b_0}, \quad Z = \frac{z}{h_0}, \quad T = \frac{t}{t_0}, \quad \bar{u} = \frac{u}{u_0}$$

$$\bar{v} = \frac{v}{v_0}, \quad \bar{w} = \frac{w}{w_0}, \quad \bar{\rho} = \frac{\rho}{\rho_0}, \quad \bar{\eta} = \frac{\eta}{\eta_0}, \quad P = \frac{h_0^2 p}{\eta_0 u_0 l_0}$$

- Reynolds number:

$$\mathcal{R} = \frac{\text{Inertia}}{\text{Viscous}} = \frac{\rho_0 u_0 l_0}{\eta_0}$$

- Thin fluid film: $h_0 \ll l_0, \quad \mathcal{R} \ll 1$

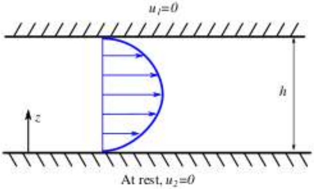
$$\frac{\partial p}{\partial x} = \frac{\partial}{\partial z}\left(\frac{\partial u}{\partial z}\right)$$

$$\frac{\partial p}{\partial y} = \frac{\partial}{\partial z}\left(\frac{\partial v}{\partial z}\right)$$

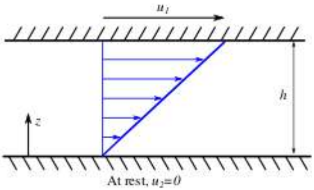
$$\frac{\partial p}{\partial z} = 0 \rightarrow p = p(x,y)$$

Velocity profile

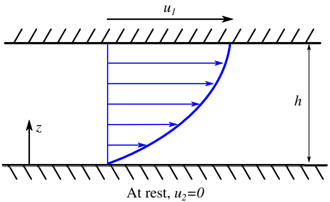
$$u = \underbrace{\frac{\partial p}{\partial x}\frac{z^2 - zh}{2\eta}}_{\text{Poiseuille flow}} + \underbrace{u_1 \frac{z}{h} + u_2\left(1 - \frac{z}{h}\right)}_{\text{Couette flow}}$$



Poiseuille flow



Couette flow



Calculating flow rates

$$u = \frac{\partial p}{\partial x}\frac{z^2 - zh}{2\eta} + u_1\frac{z}{h} + u_2\left(1 - \frac{z}{h}\right)$$

$$v = \frac{\partial p}{\partial y}\frac{z^2 - zh}{2\eta} + v_1\frac{z}{h} + v_2\left(1 - \frac{z}{h}\right)$$

Flow rate per unit width in x and y directions:

$$q_x' = \int\limits_0^h u dz = -\frac{h^3}{12\eta}\frac{\partial p}{\partial x} + \frac{u_1 + u_2}{2}h$$

$$q_y' = \int\limits_0^h v dz = -\frac{h^3}{12\eta}\frac{\partial p}{\partial y} + \frac{v_1 + v_2}{2}h$$

Integrating continuity equation across film thickness:

$$\int\limits_0^h \left[\frac{\partial \rho}{\partial t} + \nabla \cdot \underline{\boldsymbol{u}}\right] dz = 0$$

- General form in 3D:

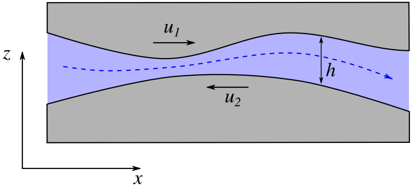
$$\frac{\partial}{\partial x}\left(\frac{\rho h^3}{12\eta}\frac{\partial p}{\partial x}\right)+\frac{\partial}{\partial y}\left(\frac{\rho h^3}{12\eta}\frac{\partial p}{\partial y}\right)=\frac{(u_1+u_2)}{2}\frac{\partial(\rho h)}{\partial x}+\frac{(v_1+v_2)}{2}\frac{\partial(\rho h)}{\partial y}+h\frac{\partial\rho}{\partial t}$$

- If ρ, η are constant:

$$\frac{1}{12\eta}\frac{\partial}{\partial x}\left(h^3\frac{\partial p}{\partial x}\right)+\frac{1}{12\eta}\frac{\partial}{\partial y}\left(h^3\frac{\partial p}{\partial y}\right)=\frac{(u_1+u_2)}{2}\frac{\partial h}{\partial x}+\frac{(v_1+v_2)}{2}\frac{\partial h}{\partial y}$$

- In 2D:

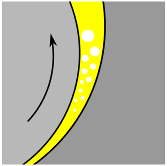
$$\frac{\partial}{\partial x}\left(h^3\frac{\partial p}{\partial x}\right)=6\eta(u_1+u_2)\frac{\partial h}{\partial x}$$



O. Reynolds (1886)

Physically relevant models

- Non-Newtonian fluid:
$$\eta = f\left(\frac{du}{dz}\right)$$
- Viscosity-pressure dependency: Barus law
$$\eta(p) = \eta_0 e^{\alpha p}$$
- Fluid compressibility:
$$K = -V\frac{dp}{dV} = \rho\frac{dp}{d\rho}$$
$$\rho = \rho_0 e^{(p-p_0)/K}$$
- Cavitation: process of bubble generation due to local pressure decline below saturated vapor pressure



Step slider bearing

- Reynolds equation
  ($\rho = \text{const}, \eta = \text{const}$):

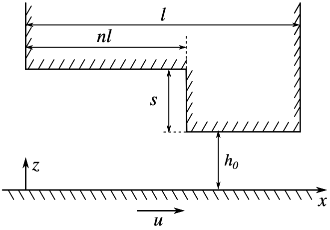
$$\frac{d}{dx}\left(h^3\frac{dp}{dx}\right) = 6u\eta\frac{dh}{dx}$$

- Constant film thickness in both sections:

$$h(x) = \begin{cases} h_0 + s & 0 < x < nl \\ h_0 & nl < x < l \end{cases}$$

$$\frac{d^2p}{dx^2} = 0, \quad x \in (0; nl) \cup (nl; l)$$

$$\frac{dp}{dx} = const, \quad x \in (0; nl) \cup (nl; l)$$

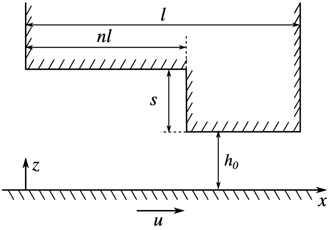


Step slider bearing

- Continuity of pressure:

$$p|_{x=nl-0} = p|_{x=nl+0} = p_m$$

$$nl\left(\frac{dp}{dx}\right)_i = -(1-n)l\left(\frac{dp}{dx}\right)_o$$



- Continuity of flow rate:

$$q'_{x,i} = q'_{x,o}$$

$$-\frac{(h_0+s)^3}{12\eta}\left(\frac{dp}{dx}\right)_i + \frac{u(h_0+s)}{2} = -\frac{h_0^3}{12\eta}\left(\frac{dp}{dx}\right)_o + \frac{uh_0}{2}$$

- Maximum pressure:

$$p_m = 6\eta ul\left[\frac{n(1-n)s}{(1-n)(h_0+s)^3 + nh^3}\right]$$

Step slider bearing

- Pressure distribution:

$$p(x) = \begin{cases} p_m \dfrac{x}{nl} & 0 < x < nl \\ p_m \dfrac{l - x}{(1-n)l} & nl < x < l \end{cases}$$

$$p_m = 6\eta u l \left[\frac{n(1-n)s}{(1-n)(h_0+s)^3 + nh^3} \right]$$

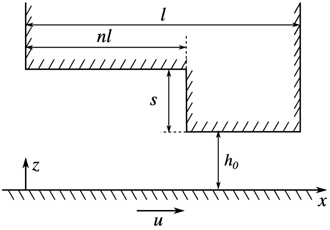
- Optimal bearing configuration to produce the largest p_m:

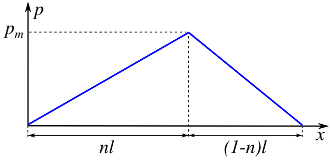
$$\frac{\partial p_m}{\partial n} = 0 \quad \text{and} \quad \frac{\partial p_m}{\partial s} = 0$$

$$\begin{cases} (1-n)^2(h_0+s)^3 - n^2 h_0^3 = 0 \\ (1-n)(h_0+s)^2(h_0-2s) + nh_0^3 = 0 \end{cases}$$

- Optimal values:

$$\frac{h_0}{s} = 1.155, \quad n = 0.7182$$





Inclined slider bearing

- Reynolds equation
  ($\rho = \text{const}, \eta = \text{const}$):

$$\frac{d}{dx}\left(h^3 \frac{dp}{dx}\right) = 6u\eta \frac{dh}{dx}$$

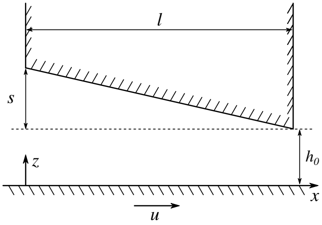
- Integrating:

$$h^3 \frac{dp}{dx} = 6u\eta h + C$$

$$\frac{dp}{dx} = 0 \to h = h_m \Longrightarrow C = 6u\eta h_m$$

$$\frac{dp}{dx} = 6\eta u \left(\frac{h - h_m}{h^3}\right)$$

$$h(x) = h_0 + s\left(1 - \frac{x}{l}\right)$$



- Introducing dimensionless variables:

$$X = \frac{x}{l}, \quad H = \frac{h}{s}, \quad H_m = \frac{h_m}{s}, \quad H_0 = \frac{h_0}{s} \Longrightarrow \quad P = \frac{ps^2}{\eta u l}$$

Inclined slider bearing

- Dimensionless Reynolds equation:

$$\frac{dP}{dX} = 6\left(\frac{H - H_m}{H^3}\right)$$

$$H = H_0 + 1 - X, \quad \frac{dH}{dX} = -1$$

- Integrating:

$$P = 6\int\left(\frac{1}{H^2} - \frac{H_m}{H^3}\right)dX = 6\left(\frac{1}{H} - \frac{H_m}{2H^2}\right)+C$$

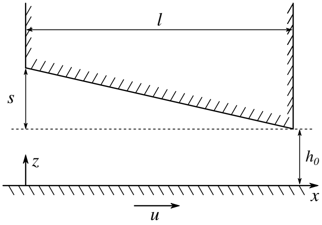
- BCs:

$$P = 0 \text{ when } X = 0 \to H = H_0 + 1$$

$$P = 0 \text{ when } X = 1 \to H = H_0$$

$$H_m = \frac{2H_0(1 + H_0)}{1 + 2H_0}, \quad C = -\frac{6}{1 + 2H_0}$$

$$P(X) = \frac{6X(1 - X)}{(H_0 + 1 - X)^2(1 + 2H_0)}$$



Inclined slider bearing

- Dimensionless pressure distribution:

$$P(X) = \frac{6X(1-X)}{(H_0+1-X)^2(1+2H_0)}$$

- Dimensionless coordinate of maximum:

$$X_m = \frac{1+H_0}{1+2H_0}$$

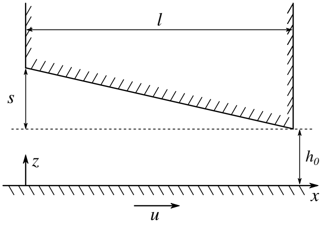
- Dimensionless maximal pressure:

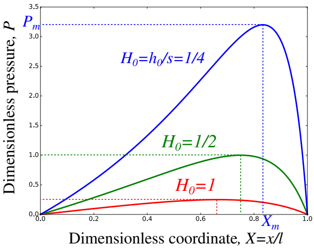
$$P_m = \frac{3}{2H_0(1+H_0)(1+2H_0)}$$

- Dimensional maximal pressure:

$$p = P\frac{\eta u l}{s^2}, \quad p_m = \frac{3\eta u l s}{2h_0(s+h_0)(s+2h_0)}$$

- Optimal shoulder height:
$\partial p_m/\partial s = 0 \to s_{\text{opt}} = \sqrt{2}h_0$





Elastohydrodynamic lubrication (EHL)

- Non-conforming surfaces
- Elastic deflection of solid walls
- Viscosity-pressure dependence:
  $\eta(p) = \eta_0 \, \exp \xi p$
- Hard EHL (metal parts):

  $0.5 \text{ GPa} \le p \le 3 \text{ GPa}$

  $0.1\ \mu\text{m} \le h_{\text{min}} \le 1\ \mu\text{m}$

  - gears
  - rolling bearings
  - cams
- Soft EHL (polymer):

  $p \approx 1 \text{ MPa}$

  $h_{\text{min}} \approx 1\ \mu\text{m}$

  - seals
  - human joints
  - tires

Needle roller bearing
www.farazbearing.com

Bevel gear www.linngear.com

Elastohydrodynamic lubrication (EHL)

- Non-conforming surfaces
- Elastic deflection of solid walls
- Viscosity-pressure dependence:
  $\eta(p) = \eta_0 \, \exp \xi p$
- Hard EHL (metal parts):

  $0.5 \text{ GPa} \le p \le 3 \text{ GPa}$

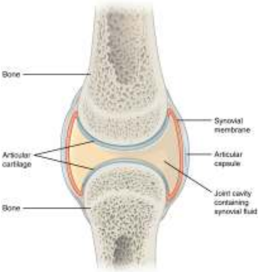
  $0.1 \, \mu\text{m} \le h_{\text{min}} \le 1 \, \mu\text{m}$

  - gears
  - rolling bearings
  - cams
- Soft EHL (polymer):

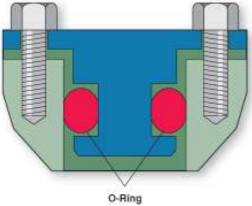
  $p \approx 1 \text{ MPa}$

  $h_{\text{min}} \approx 1 \, \mu\text{m}$

  - seals
  - human joints
  - tires



Nontrivial joint
www.wikipedia.org



O-ring seal
www.ecosealthailand.com

Elastohydrodynamic lubrication (EHL)

- Reynolds equation:

$$\frac{d}{dx}\left(\frac{h^3}{\eta}\frac{dp}{dx}\right) = 12u\frac{dh}{dx}$$

- Viscosity-pressure dependence (Barus law):

$$\eta(p) = \eta_0\, e^{\xi p}$$

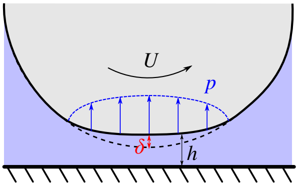
- Film shape:

$$h(x) = h_0 + S(x) + \delta(x)$$

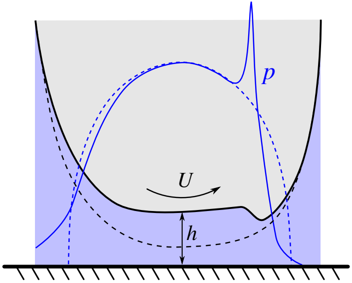
h_0	constant
$S(x) = \dfrac{x^2}{2R}$	undeformed geometry
$\delta(x)$	elastic deformation

- Contact constraints:

$$\begin{cases} h_0 + S(x) + \delta(x) = 0, & p > 0 \\ h_0 + S(x) + \delta(x) > 0, & p = 0 \end{cases}$$



Coupling of fluid and elastic problems



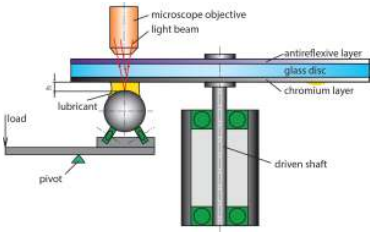
Results of numerical simulations[1,2]

[1] D. Dowson, *Wear (1995)*

[2] B.J. Hamrock, "Fundamental of fluid film lubrication"" (1991)

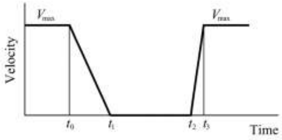
EHL film thickness: experimental observation

- Ball-on-disk optical tribometer
- Measurement based on light interference principle
- Unidirectional start-stop-start motion
- Important for study of rolling contact fatigue and wear



Ball-on-disk apparatus with interferometry[2]

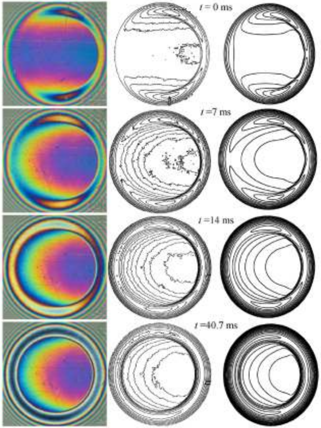
[2] D. Kostal et al, *Journal of Tribology (2017)*



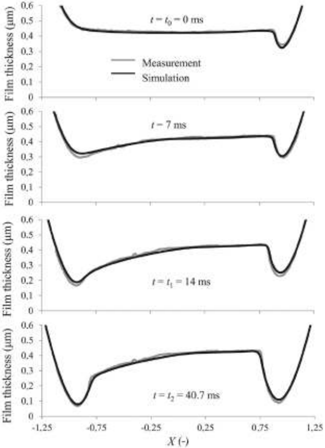
Unidirectional start-stop-start motion[1]

[1] P. Sperka et al, *Journal of Tribology (2014)*

EHL film thickness: experimental observation



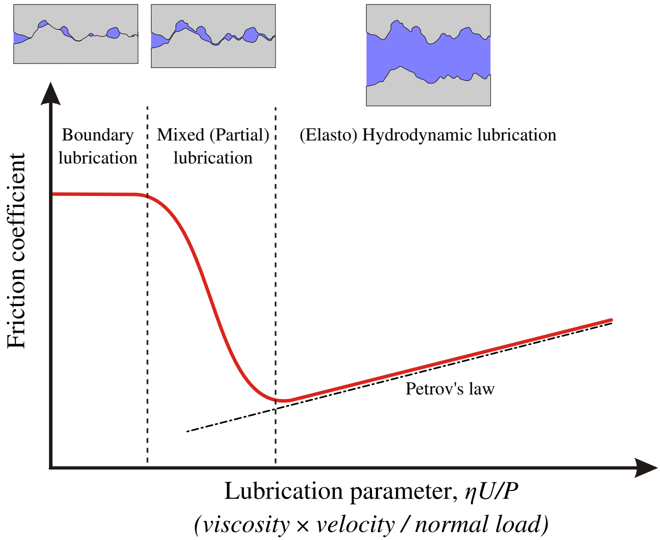
Left to right:
snapshots of interferograms, film thickness contour maps, results of numerical simulation[1]



Midplane film thickness profiles along rolling direction[1]

[1] P. Sperka et al, *Journal of Tribology (2014)*

Lubrication regimes: Stribeck curve



Adapted from `www.wikipedia.org`

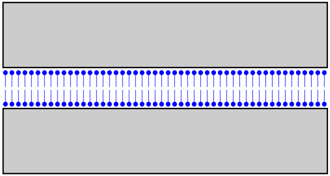
Boundary lubrication

- Asperities come in contact
- $1\ \text{nm} \le h_{\text{min}} \le 10\ \text{nm}$
- Bulk lubricant properties (i.e. viscosity) are not important
- Physical and chemical properties of the surface and of the fluid film are important
- Lubricant film of molecular size[1]
- Breakdown of lubricant film at localized regions[2], frictional force:

$$F = A\,(\alpha s_m + (1-\alpha)s_l)$$

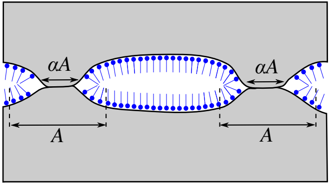
A	the area that supports the load
α	fraction of breakdown area
s_m	shear stress in solid contact
s_l	shear stress in the lubricating film

Therefore, if α - const, then $F \propto A$.



The frictional resistance is due to interaction between the outer surfaces of the adsorbed monolayers without any solid contact occurring [1]

[1] W.B. Hardy, (1936)



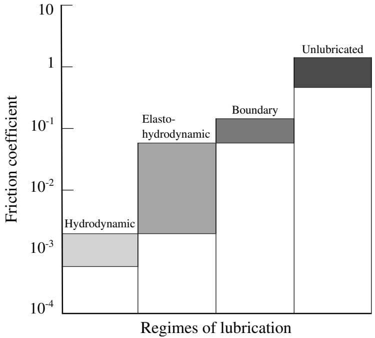
Mechanism involving breakdown of the lubricant film at small localized regions[2]

[1] F.P. Bowden and D. Tabor, "The friction and Lubrication of Solids (1950)

Mixed (partial) lubrication

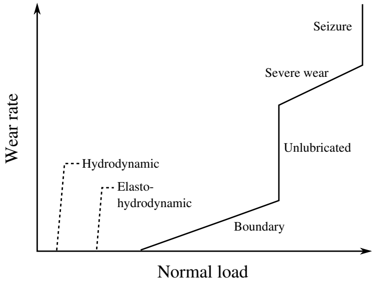
- Combination of boundary and fluid film effects
- Some asperity contact
- Film layer of one or more molecular layers
- Smooth transition
- $0.01\ \mu\text{m} \le h_{\text{min}} \le 1\ \mu\text{m}$

Lubrication: friction coefficient and wear



Bar diagram of friction coefficient for various lubrication conditions

B.J. Hamrock, "Fundamental of fluid film lubrication" (1991)



Wear rate for various lubrication regimes

Beerbower (1972)

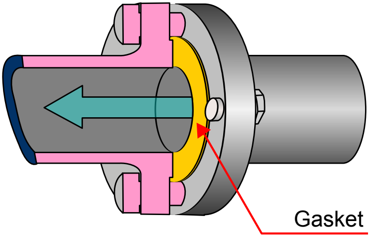
Lubrication: take home messages

- Lubrication: reduction of wear and friction between relatively moving surfaces by adding lubricant
- Hydrodynamic: full separation of solids, thin fluid film lubrication (Reynolds equation), dynamic viscosity is important
- EHL: solids deform elastically (hard - metals, soft - polymers), affected by viscosity-pressure dependence
- Boundary: contact of asperities, but still thin molecular level of lubricant, chemical properties important, breakdown of fluid film
- Mixed (partial): smooth transition
- Recommended literature:

1. B.J. Hamrock et al, "Fundamentals of fluid film lubrication" (2004)
2. F.P. Bowden and D. Tabor, "The friction and Lubrication of Solids (1950)
3. D. Dowson, "Elastohydrodynamic and micro-elastohydrodynamic lubrication", *Wear, 190 (1995)*

Sealing: what is it?

- **Sealing:** technique to prevent or reduce leakage of fluid from one chamber to another using seals
- Different types:
  - face seals
  - O-ring seals
  - labyrinth seals
- Dynamic/static
- Material: polymer/metallic
- Operate in EHL/mixed/boundary regimes



Face seal

O-ring

Application: metal-to-metal static face seal

- Metal-to-metal static face seals used in fluid system of nuclear power plants
- Coting of the seal is made of material Norem[1]: elasto-plastic
  Elastic moduli:

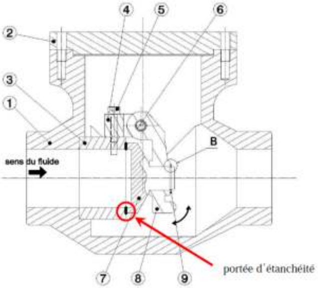
$$E = 175\text{ GPa}, \nu = 0.3$$

Yield stress:

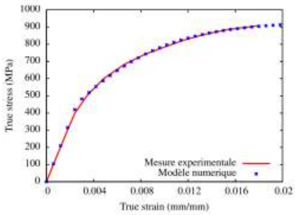
$$\sigma_Y = R_0 + Q(1 - e^{-bp})$$

$R_0 = 442.7$ MPa
$Q = 493.5$ MPa
$b = 242.2$

J. Durand, PhD thesis (2012)

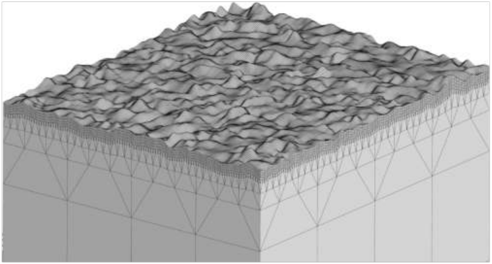


Sketch of a valve[1]

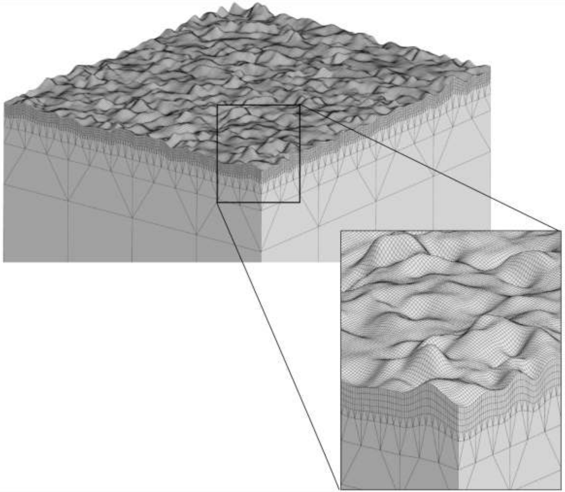


Material behavior of Norem[1]

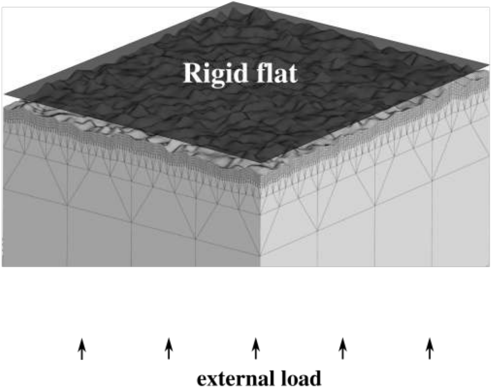
Problem statement



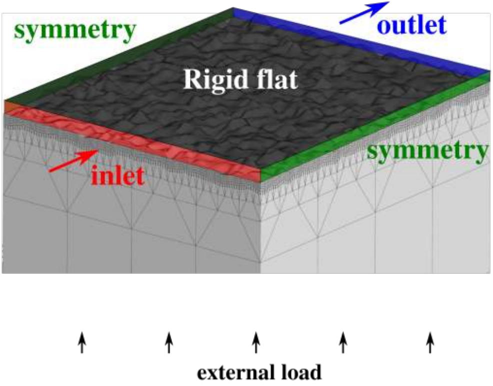
Problem statement



Problem statement



Problem statement



Surface discretization	Total DOFs	RAM	Cores	Time
256×256	1.4M	30 Gb	8	2-4 days
512×512	5.7M	140 Gb	16	4-8 days

Problem statement

- Mechanical contact (unilateral):

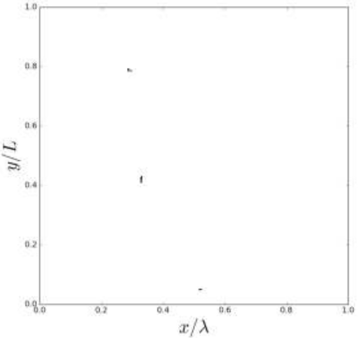
$$\begin{cases} \nabla \cdot \underline{\underline{\sigma}}(\underline{\boldsymbol{u}}) = 0 & \text{in } \Omega_s, \\ g(\underline{\boldsymbol{u}}) \geq 0,\ \sigma_n(\underline{\boldsymbol{u}}) \leq 0,\ g(\underline{\boldsymbol{u}})\,\sigma_n(\underline{\boldsymbol{u}}) = 0 & \text{at } \Gamma_c, \\ u_x|_{x=0,\lambda/2} = 0, \quad u_y\big|_{y=0,L} = 0, & \end{cases}$$

- Thin fluid flow with immobile walls (Reynolds equation):

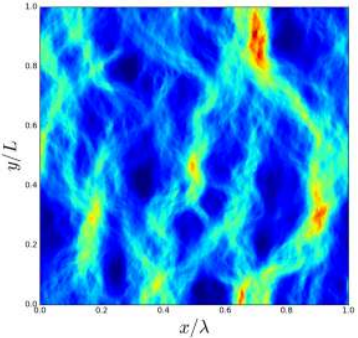
$$\begin{cases} \nabla \cdot \left[g(\underline{\boldsymbol{u}})^3 \nabla p_f \right] = 0 & \text{in } \Gamma_f \\ p_f\big|_{y=0} = p_i, \quad p_f\big|_{y=L} = p_o & \\ [\nabla p_f \cdot \underline{\boldsymbol{e}}_x]\big|_{x=0,\lambda/2} = 0, & \end{cases}$$

- Fluid/structure interface:

$$\sigma_n(\underline{\boldsymbol{u}}) = -p_f \quad \text{at } \Gamma_f$$

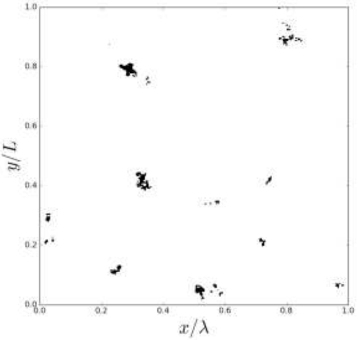


Morphology of the contact interface

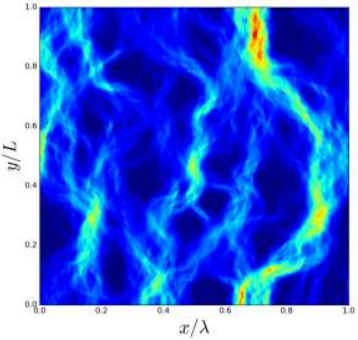


Intensity of the fluid flux

Results of the numerical simulation

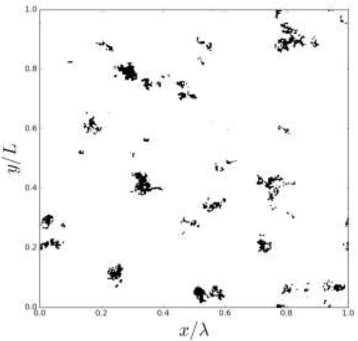


Morphology of the contact interface

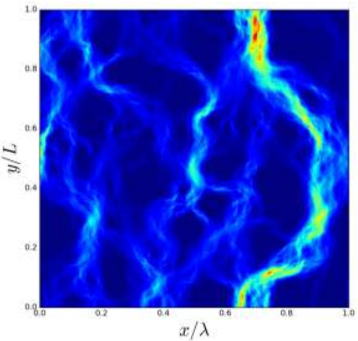


Intensity of the fluid flux

Results of the numerical simulation

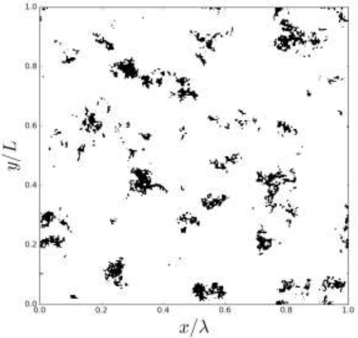


Morphology of the contact interface

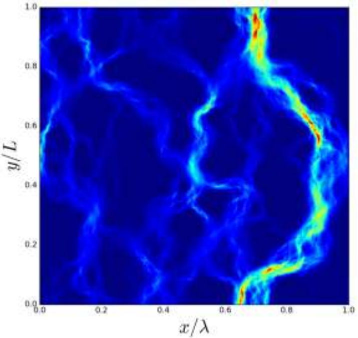


Intensity of the fluid flux

Results of the numerical simulation

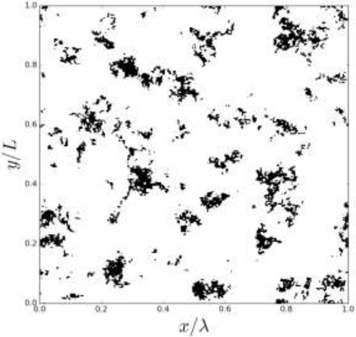


Morphology of the contact interface

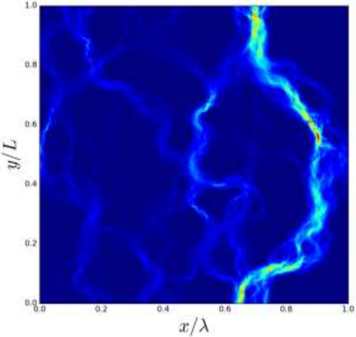


Intensity of the fluid flux

Results of the numerical simulation

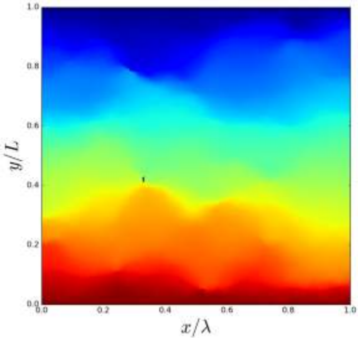


Morphology of the contact interface

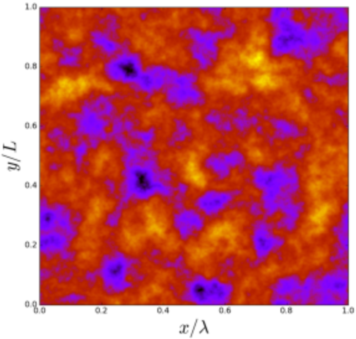


Intensity of the fluid flux

Results of the numerical simulation

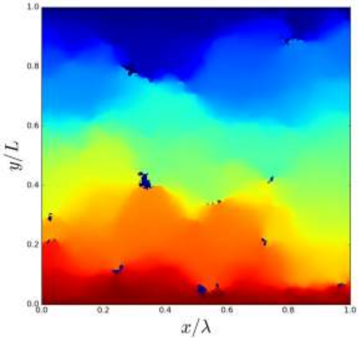


Distribution of the fluid pressure

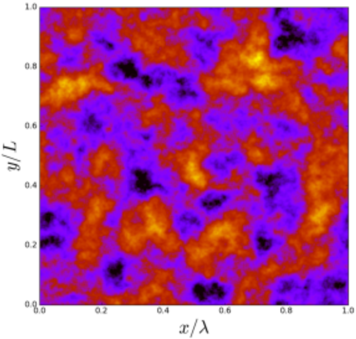


Distribution of the free volume

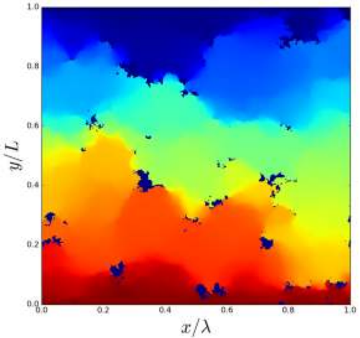
Results of the numerical simulation



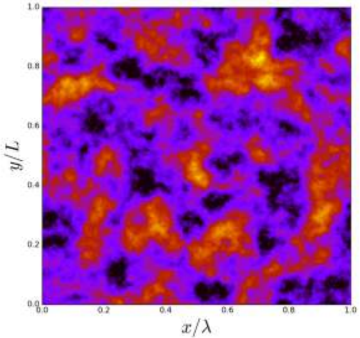
Distribution of the fluid pressure



Distribution of the free volume

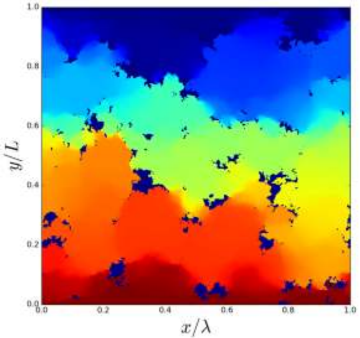


Distribution of the fluid pressure

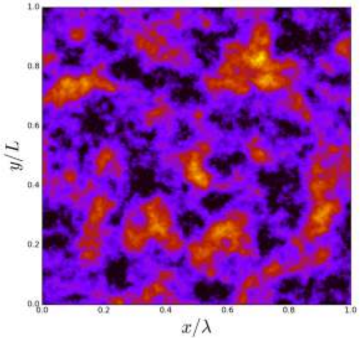


Distribution of the free volume

Results of the numerical simulation

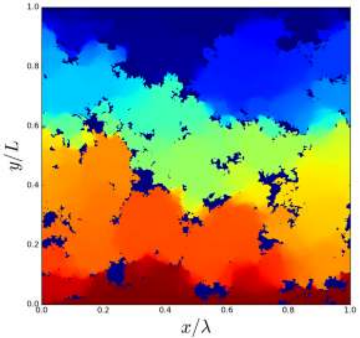


Distribution of the fluid pressure

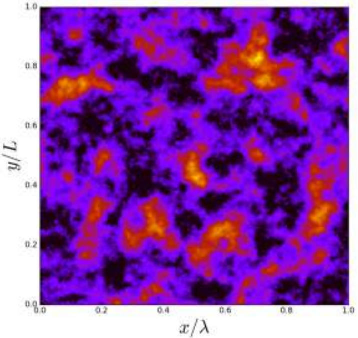


Distribution of the free volume

Results of the numerical simulation

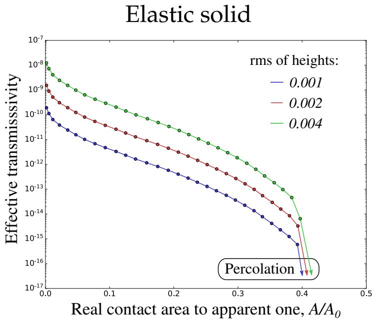


Distribution of the fluid pressure



Distribution of the free volume

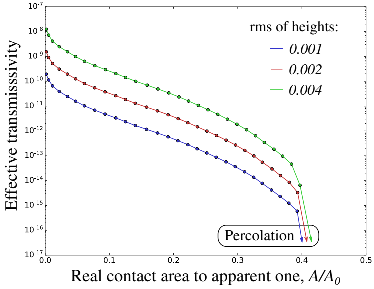
Transmissivity of the interface



Effective transmissivity of the interface
in case of elastic material
(loading until percolation)

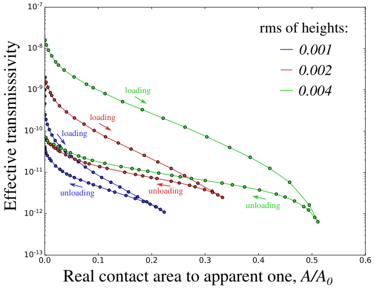
Transmissivity of the interface

Elastic solid



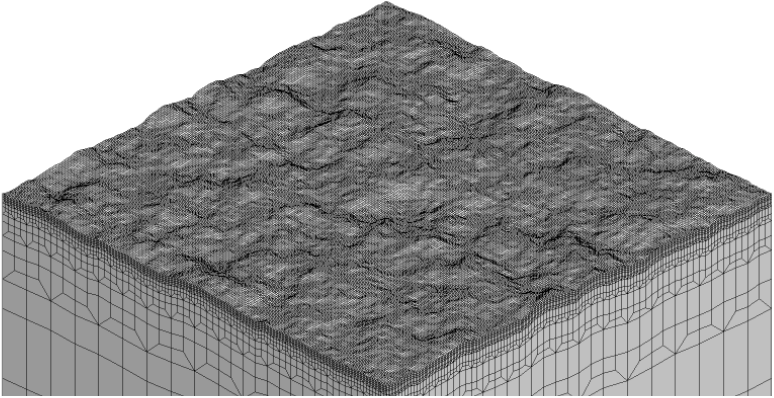
Effective transmissivity of the interface
in case of elastic material
(loading until percolation)

Elasto-plastic solid



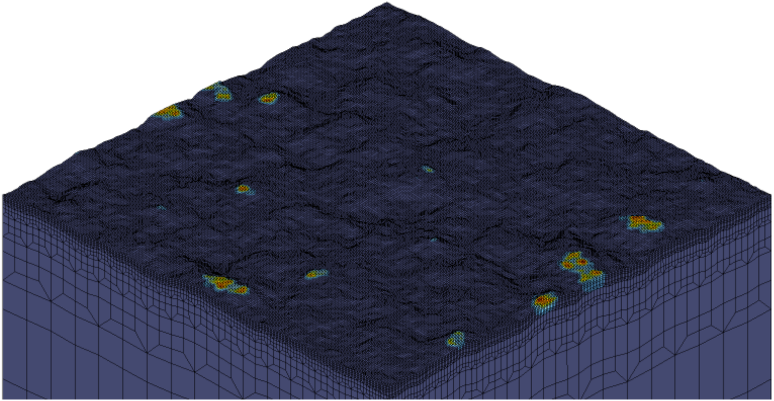
Effective transmissivity of the interface
in case of elasto-plastic material
(loading-unloading cycle)

FE Results



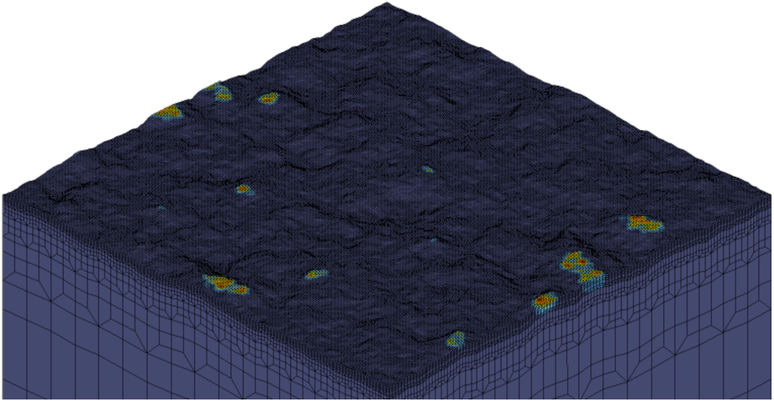
FE mesh

FE Results



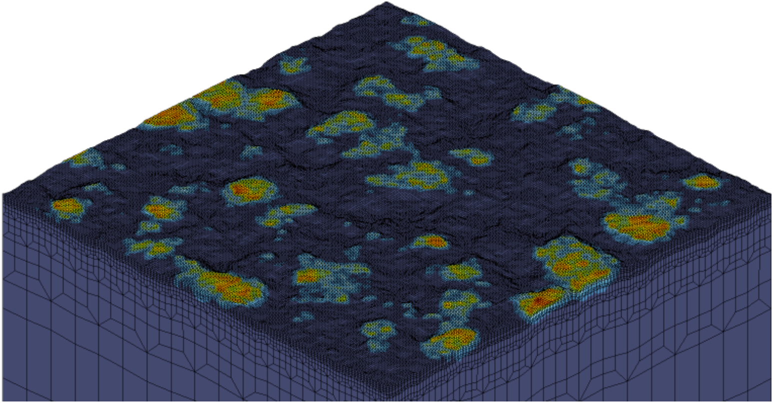
Accumulated plastic strain during *loading*

FE Results



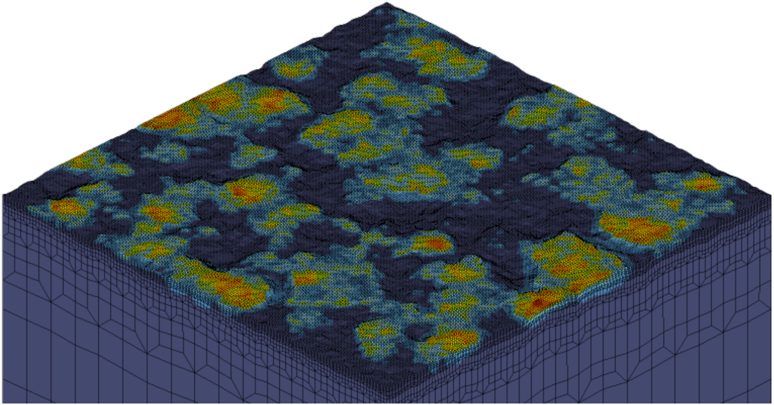
Accumulated plastic strain during *loading*

FE Results



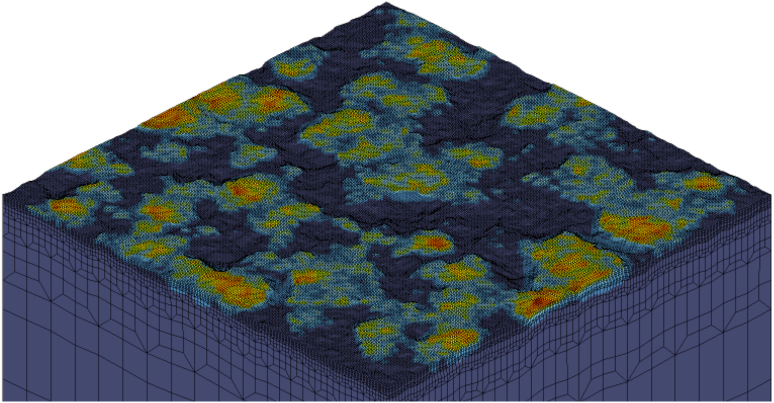
Accumulated plastic strain during *loading*

FE Results



Accumulated plastic strain during *loading*

FE Results



Accumulated plastic strain during *unloading*

Thank you for your attention!